

PRELIMINARY

YDA179

Application Manual

D-707Di digital input stereo 20W digital audio power amplifier

The information provided is preliminary, and subject to change without notice. Please check for the latest information when using this product in your design.

YAMAHA CORPORATION

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PRECAUTIONS AND INSTRUCTIONS FOR SAFETY



WARNING



Prohibited

Do not use the device under stresses beyond those listed in Absolute Maximum Ratings. Such stresses may become causes of breakdown, damages, or deterioration, causing explosion or ignition, and this may lead to fire or personal injury.



Prohibited

Do not mount the device reversely or improperly and also do not connect a supply voltage in wrong polarity. Otherwise, this may cause current and/or power-consumption to exceed the absolute maximum ratings, causing personal injury due to explosion or ignition as well as causing breakdown, damages, or deterioration. And, do not use the device again that has been improperly mounted and powered once.



Prohibited

Do not short between pins. In particular, when different power supply pins, such as between high-voltage and low-voltage pins, are shorted, smoke, fire, or explosion may take place.



Instructions

As to devices capable of generating sound from its speaker outputs, please design with safety of your products and system in mind, such as the consequences of unusual speaker output due to a malfunction or failure. A speaker dissipates heat in a voice-coil by air flow accompanying vibration of a diaphragm. When a DC signal (several Hz or less) is input due to device failure, heat dissipation characteristics degrade rapidly, thereby leading to voice-coil burnout, smoking or ignition of the speaker even if it is used within the rated input value.



CAUTION



Prohibited

Do not use Yamaha products in close proximity to burning materials, combustible substances, or inflammable materials, in order to prevent the spread of the fire caused by Yamaha products, and to prevent the smoke or fire of Yamaha products due to peripheral components.



Instructions

Generally, semiconductor products may malfunction and break down due to aging, degradation, etc. It is the responsibility of the designer to take actions such as safety design of products and the entire system and also fail-safe design according to applications, so as not to cause property damage and/or bodily injury due to malfunction and/or failure of semiconductor products.

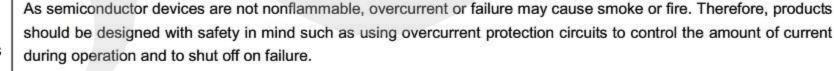


Instructions



Instructions

The built-in DSP may output the maximum amplitude waveform suddenly due to malfunction from disturbances etc. and this may cause damage to headphones, external amplifiers, and human body (the ear). Please pay attention to safety measures for device malfunction and failure both in product and system design.





Instructions

Products should be designed with fail safe in mind in case of malfunction of the built-in protection circuits. Note that the built-in protection circuits such as overcurrent protection circuit and high-temperature protection circuit do not always protect the internal circuits. In some cases, depending on usage or situations, such protection circuit may not work properly or the device itself may break down before the protection circuit kicks in.



Instructions



Instructions





Instructions



Instructions

Use a robust power supply. The use of an unrobust power supply may lead to malfunctions of the protection circuit, causing device breakdown, personal injury due to explosion, or smoke or fire.

Product's housing should be designed with the considerations of short-circuiting between pins of the mounted device due to foreign conductive substances (such as metal pins etc.). Moreover, the housing should be designed with spatter prevention etc. due to explosion or burning. Otherwise, the spattered substance may cause bodily injury.

The device may be heated to a high temperature due to internal heat generation during operation. Therefore, please take care not to touch an operating device directly.

Electrostatic discharges can damage and destroy semiconductor devices. Pay close attention to static build-up when handling devices.

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1. Features

- 16/18/20/24-bit input with I²S, Left-alignment and Right-alignment data format
- PSNR & DR(A-weighting)
 Loudspeaker: 97dB (PSNR), 106dB (DR) @22V
- Multiple sampling frequencies (Fs)
 32kHz / 44.1kHz / 48kHz and
 64kHz / 88.2kHz / 96kHz and
 128kHz/176.4kHz/192kHz
- System clock = 64x, 128x, 256x, 384x, 512x, 768x, 1024x Fs
 256x~1024x Fs for 32kHz / 44.1kHz / 48kHz
 128x~512x Fs for 64kHz / 88.2kHz / 96kHz
 64x~256x Fs for 128kHz/176.4kHz/192kHz
- Supply voltage
 3.3V for digital circuit
 10V~22V for loudspeaker driver

Anti-pop design

- Loudspeaker output power for Stereo@22V
 10W x 2ch into 8Ω @0.13% THD+N
 15W x 2ch into 8Ω @0.16% THD+N
 20W x 2ch into 8Ω @0.22% THD+N
- Sounds processing including:
 Volume control (+24dB~-103dB, 0.125dB/step)
 Dynamic range control
 Power clipping
 Channel mixing
 User programmed noise gate
 DC-blocking high-pass filter

- Short circuit and over-temperature protection
- I²C control interface with selectable device address
- Internal PLL
- LV Under-voltage shutdown and HV Under-voltage detection
- Power saving mode
- Dynamic temperature control

2. Applications

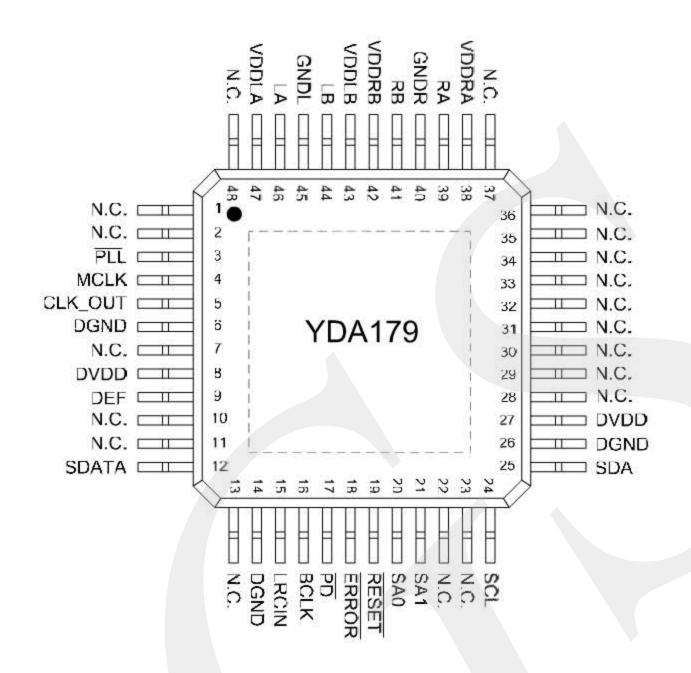
- TV audio
- Boom-box, CD and DVD receiver, docking system
- Powered speaker
- Wireless audio

3. Description

YDA179 is a digital audio amplifier capable of driving a pair of 8Ω , 20W speaker, which operate with play music at a 22V supply without external heat-sink or fan requirement.

Using I²C digital control interface, the user can control YDA179's input format selection, mute and volume control functions. YDA179 has many built-in protection circuits to safeguard YDA179 from connection errors.

4. Pin Assignment



< 48 pin SQFP Top View >

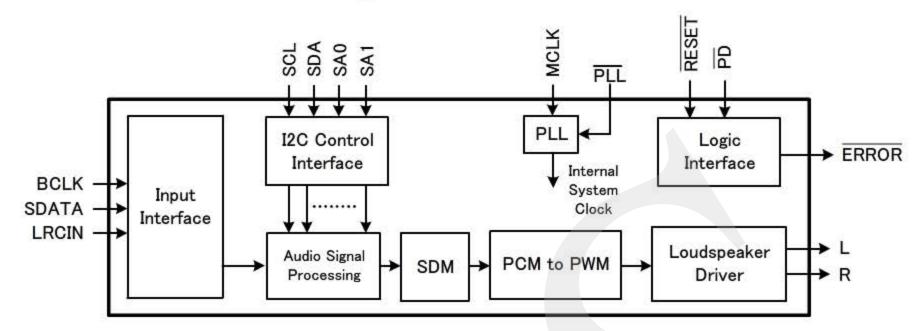
5. Pin Description

PIN	NAME	TYPE	DESCRIPTION	CHARACTERISTICS
1	N.C.			
2	N.C.			
3	PLL	Ĭ	PLL enable, low active	Schmitt trigger TTL input buffer
4	MCLK	I	Master clock input	Schmitt trigger TTL input buffer
5	CLK_OUT	0	Clock output from PLL	TTL output buffer
6	DGND	Р	Digital Ground	
7	N.C.			
8	DVDD	Р	Digital Power	
9	DEF	<u>I</u>	Default volume setting	Schmitt trigger TTL input buffer
10	N.C.			
11	N.C.			
12	SDATA	Ь	Serial audio data input	Schmitt trigger TTL input buffer
13	N.C			

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14	DGND	Р	Digital Ground	
15	LRCIN	Ī	Left/Right clock input (Fs)	Schmitt trigger TTL input buffer
16	BCLK	1	Bit clock input (64Fs)	Schmitt trigger TTL input buffer
17	PD	ſ	Power down, low active	Schmitt trigger TTL input buffer
18	ERROR	0	Error status	Open-drain output
19	RESET	L	Reset, low active	Schmitt trigger TTL input buffer
20	SA0	Ĺ	I ² C select address 0	Schmitt trigger TTL input buffer
21	SA1	I	I ² C select address 1	Schmitt trigger TTL input buffer
22	N.C			
23	N.C			
24	SCL	f	I ² C serial clock input	Schmitt trigger TTL input buffer
25	SDA	I/O	I ² C bi-directional serial data	Schmitt trigger TTL input buffer
26	DGND	Р	Digital Ground	
27	DVDD	Р	Digital Power	
28	N.C			
29	N.C			
30	N.C			
31	N.C			
32	N.C			
33	N.C			
34	N.C			
35	N.C			
36	N.C.			
37	N.C.			
38	VDDRA	Р	Right channel supply A	
39	RA	0	Right channel output A	
40	GNDR	Р	Right channel ground	
41	RB	0	Right channel output B	
42	VDDRB	Р	Right channel supply B	
43	VDDLB	Р	Left channel supply B	
44	LB	0	Left channel output B	
45	GNDL	Р	Left channel ground	
46	LA	0	Left channel output A	
47	VDDLA	Р	Left channel supply A	
48	N.C.			

6. Functional Block Diagram



7. Thermal Resistance

Package Type	$\theta_{\rm ja}(^{\circ}{\rm C/W})$	Ψ _{jt} (°C/W)	Exposed Thermal Pad
48SQFP	22.9	1.64	Yes (Note1)

Note 1.1: The thermal pad is located at the bottom of the package. To optimize thermal performance, soldering the thermal pad to the PCB's ground plane is suggested.

Note 1.2: θ_{ja} is measured on a room temperature (T_A=25°C), natural convection environment test board, which is constructed with a thermally efficient, 4-layers PCB (2S2P). The measurement is tested using the JEDEC51-5 thermal measurement standard.

8. Electrical Characteristics

8.1. Absolute Maximum Ratings

Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device.

Symbol	Parameter	Min	Max	Units
DVDD	OVDD Supply for Digital Circuit		3.6	٧
VDDL/R	Supply for Driver Stage	-0.3	24	V
Vi	Input Voltage	-0.3	3.6	V
T _{stg}	T _{stg} Storage Temperature		150	°C
T _J Junction Operating Temperature		0	150	°C

8.2. Recommended Operating Conditions

Symbol	Parameter	Тур	Units
DVDD	Supply for Digital Circuit	3.15~3.45	V
VDDL/R	Supply for Driver Stage	10~22	V
T _A	Ambient Operating Temperature	0~70	°C

8.3. General Electrical Characteristics

Condition: T_A=25 °C (unless otherwise specified).

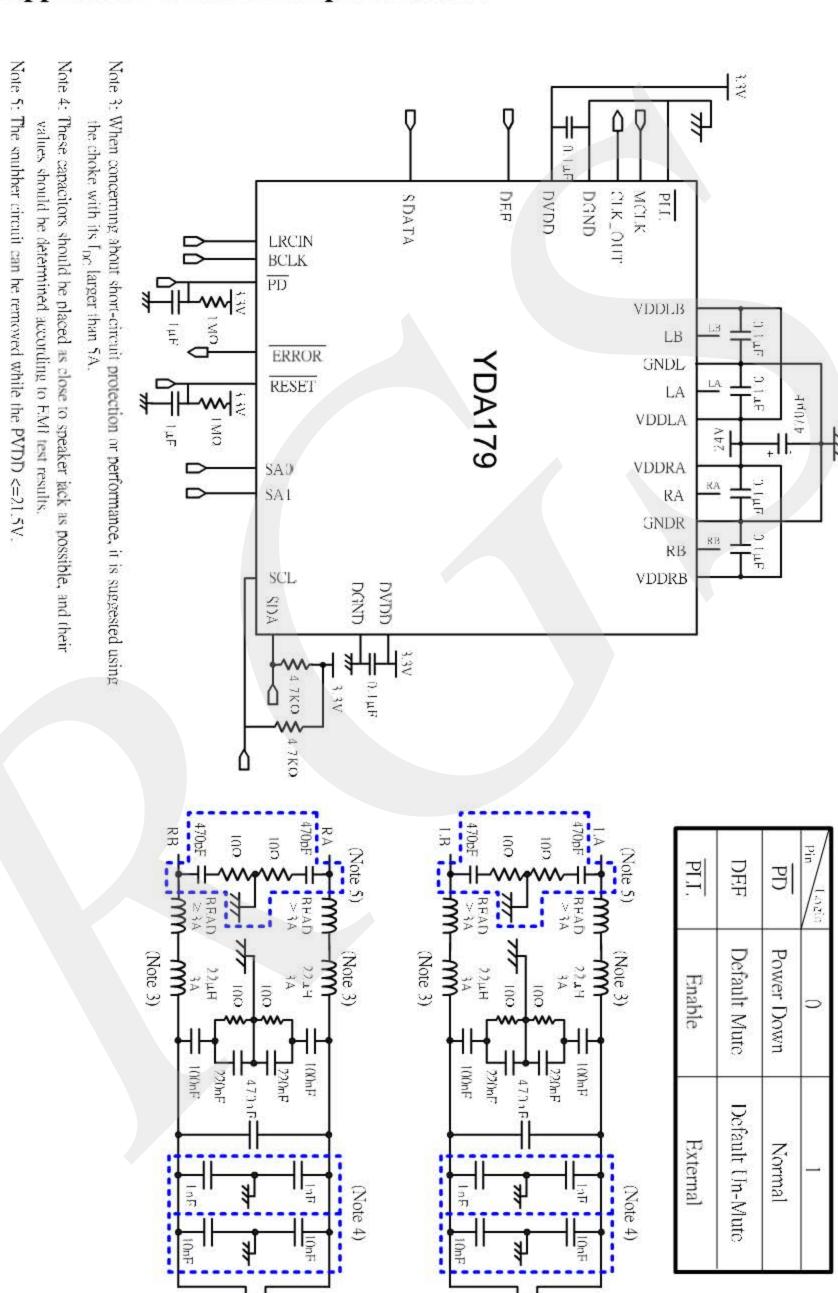
Symbol	Parameter	Condition	Min	Тур	Max	Units
I _{PD} (HV)	PVDD Supply Current during Power Down	PVDD=22V	en s	18	200	uA
I _{PD} (LV)	DVDD Supply Current during Power Down	DVDD=3.3V	2_3	4	20	uA
I _Q (HV)	Quiescent current for PVDD (50%/50% PWM duty)	PVDD=22V	910	17		mA
I _Q (LV)	Quiescent current for DVDD	DVDD=3.3V		16.5	5 25	mA
	Junction Temperature for Driver Shutdown		 -1	160	- A	°C
T _{SENSOR}	Temperature Hysteresis for Recovery from Shutdown		<u>82_6</u>	35	<u>A_8</u>	°C
UV _H	Under Voltage Disabled (For DVDD)		_	2.8	-	V
UVL	Under Voltage Enabled (For DVDD)			2.7		V
Ddo on	Static Drain-to-Source On-state Resistor, PMOS	PVDD=22V,		285	 8	mΩ
Rds-on	Static Drain-to-Source On-state Resistor, NMOS	ld=500mA	500 S	190	, 8	mΩ
I _{sc}	L(R) Channel Over-Current Protection (Note 2)	PVDD=22V	= :	5		Α
V _{IH}	High-Level Input Voltage	DVDD=3.3V	2.0	==:		V
V _{IL}	Low-Level Input Voltage	DVDD=3.3V	921	949	0.8	V
V _{OH}	High-Level Output Voltage	DVDD=3.3V	2.4			٧
V _{OL}	Low-Level Output Voltage	DVDD=3.3V		 8	0.4	٧
Cı	Input Capacitance		a 	6.4	5 - 8	pF

Note 2: Loudspeaker over-current protection is only effective when loudspeaker drivers are properly connected with external LC filters. Please refer to the application circuit example for recommended LC filter configuration.

Application Information

9.1. **Application Circuit Example for Stereo**

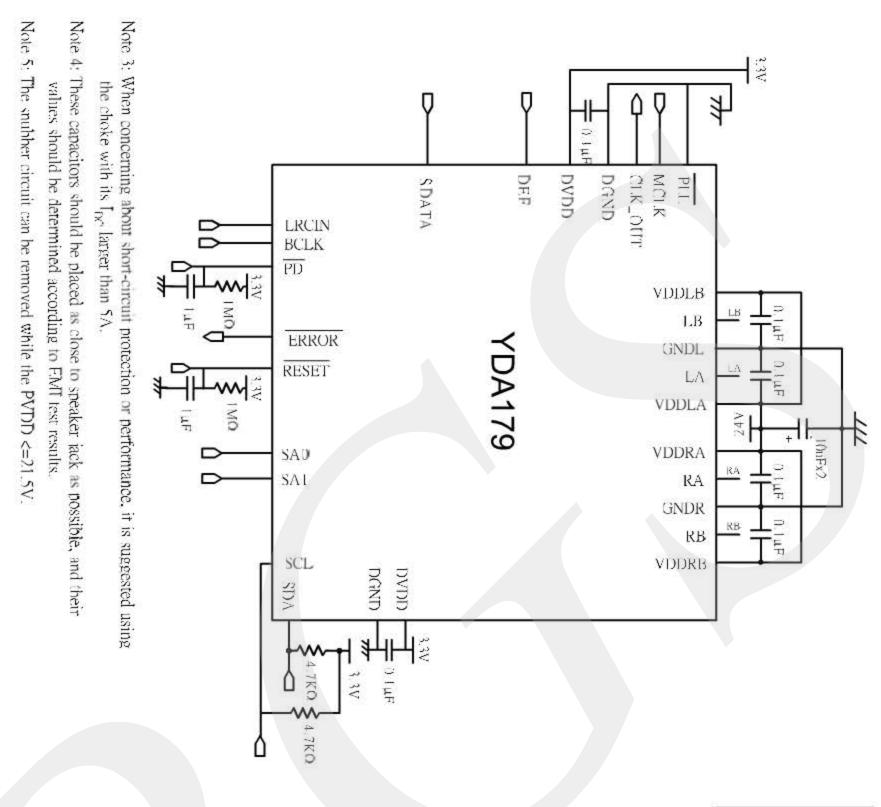


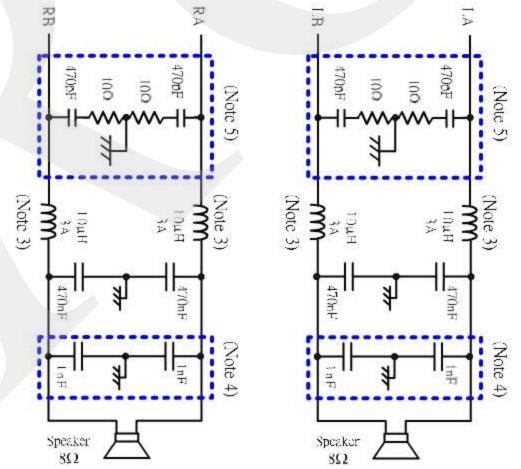


Speaker 8Ω

9.2. Application Circuit Example for Stereo (Economic type, moderate EMI suppression)

replication circuit Example for Stereo (Economic type, moderate Eight suppression)





PII.	DEF	밁	cigc.] nid
Enable	Default Mute	Power Down	0
External	Default Un-Mute	Normal	1

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10. Electrical Characteristics and Specifications for Loudspeaker

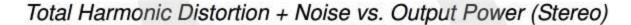
Stereo output with 22V supply voltage

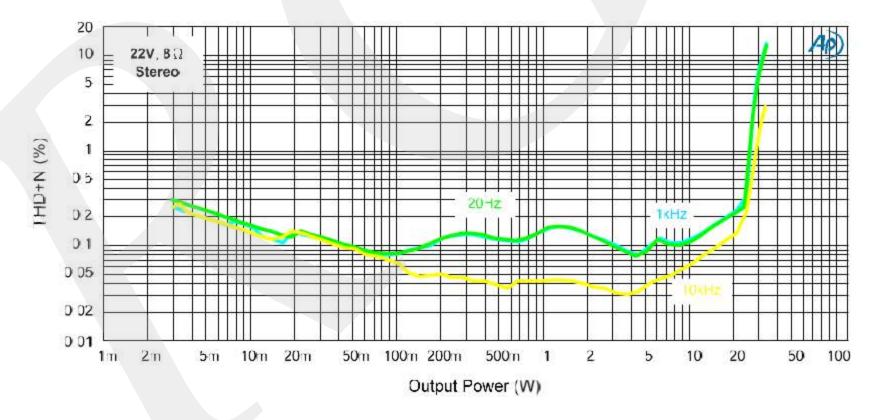
Condition: T_A =25 °C, DVDD=3.3V, VDDL=VDDR=22V, F_S =48kHz, Load=8 Ω with passive LC lowpass filter (L=22 μ H with R_{DC} =0.12 Ω , C=470nF); Input is 1kHz sinewave. Volume is 0dB unless otherwise specified.

Symbol	Parameter	Condition	Input Level	Min	Тур	Max	Units
Б	RMS Output Power (THD+N=0.22%)			<u>=</u> =	20	\$3 <u>. 5</u> 0	W
P _O	RMS Output Power (THD+N=0.16%)	+8dB volume		-	15	\$ <u>—</u>	W
(Note 9)	RMS Output Power (THD+N=0.13%)				10	s <u>—</u> :	W
THD+N	Total Harmonic Distortion + Noise	Po=7.5W			0.1	ε :	%
SNR	Signal to Noise Ratio (Note 8)	+8dB volume	-9dB		97	a c s	dB
DR	Dynamic Range (Note 8)	+8dB volume	-68dB	<u>=</u> 8	106	<u> </u>	dB
PSRR	Power Supply Rejection Ratio	VRIPPLE=1V _{RMS} at 1kHz			77	83-30	dB
	Channel Separation (non-shield choke)	Po=1W at 1kHz			70		dB

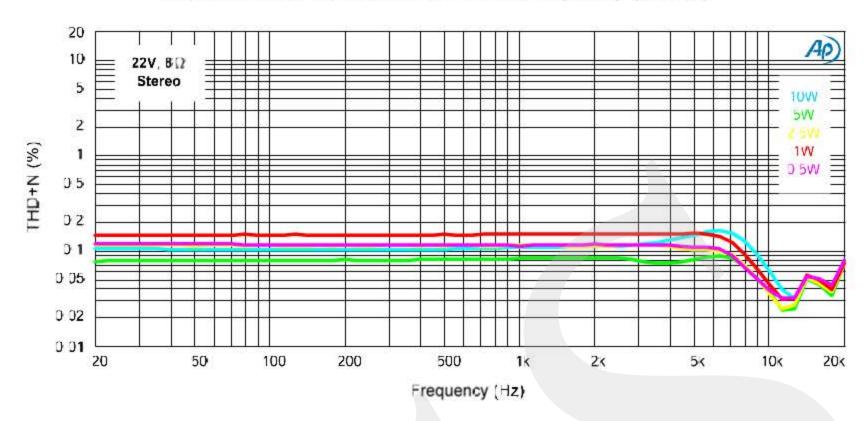
Note 8: Measured with A-weighting filter.

Note 9: Heat dissipation is limited by package type and PCB design, the external heat-sink or system cooling method should be adopted for RMS power output.

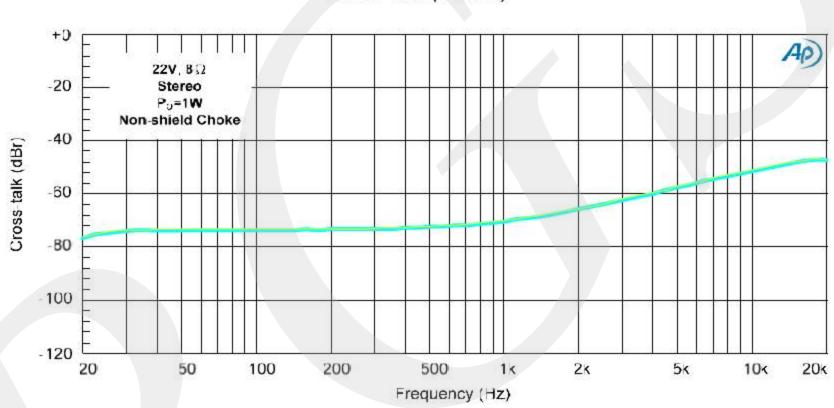




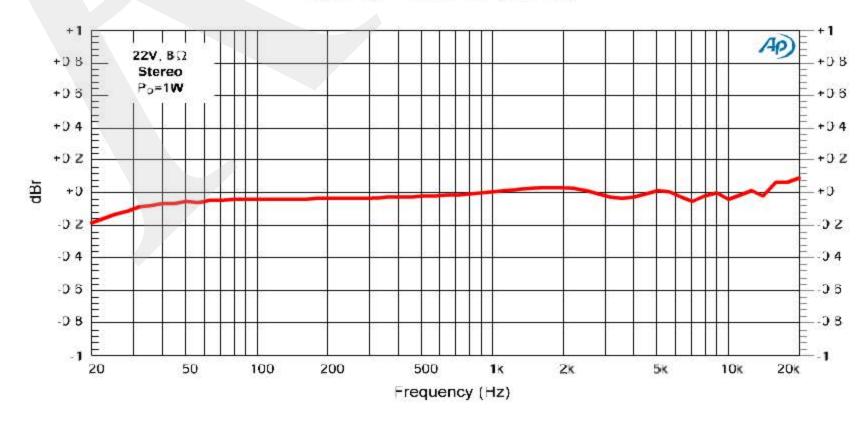
Total Harmonic Distortion + Noise vs. Frequency (Stereo)



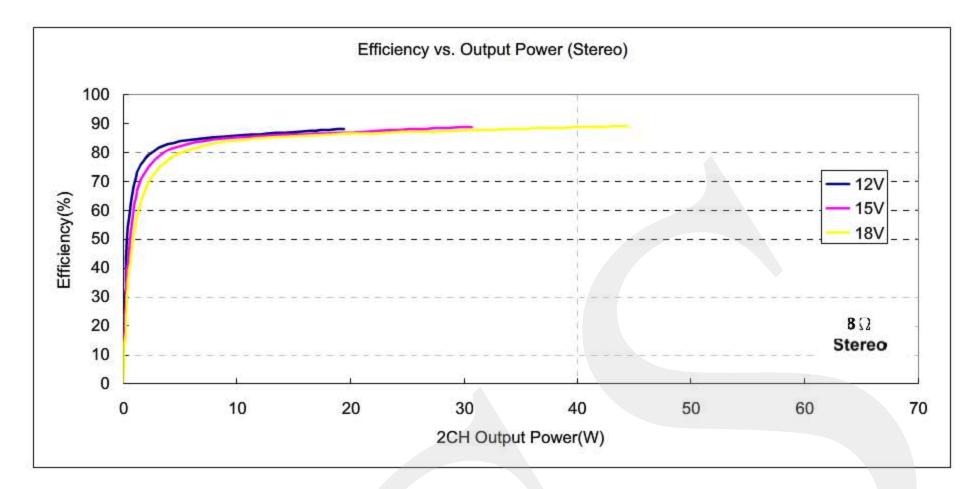
Cross-talk (Stereo)



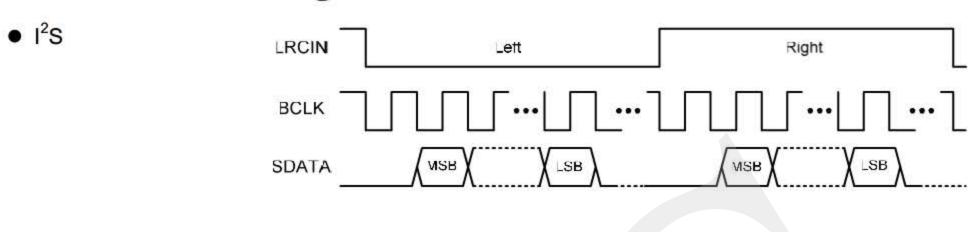
Frequency Response (Stereo)

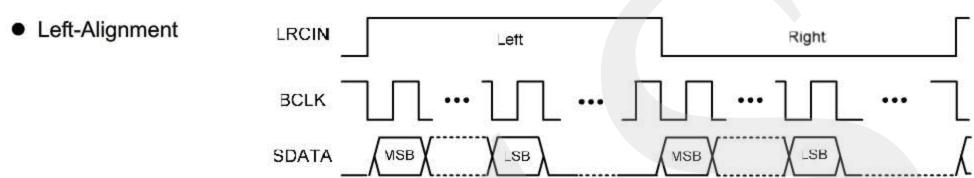


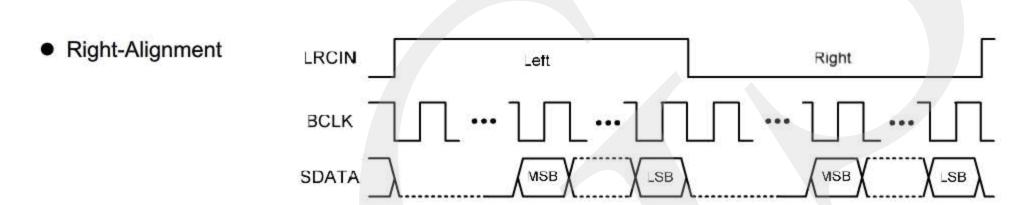
Efficiency (Stereo)



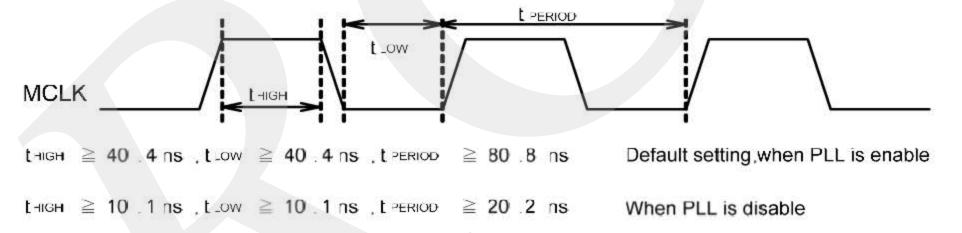
11. Interface Configuration



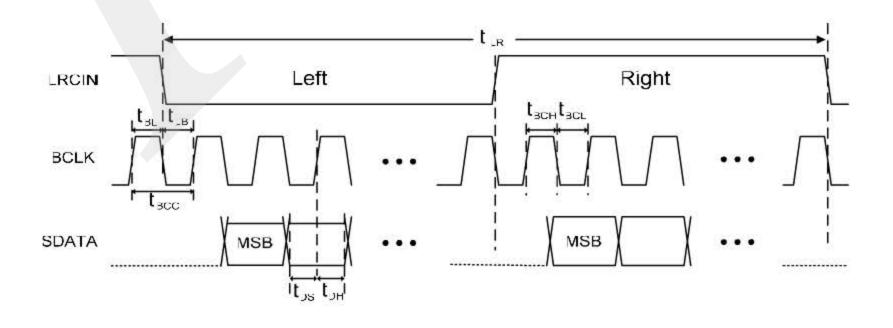




System Clock Timing

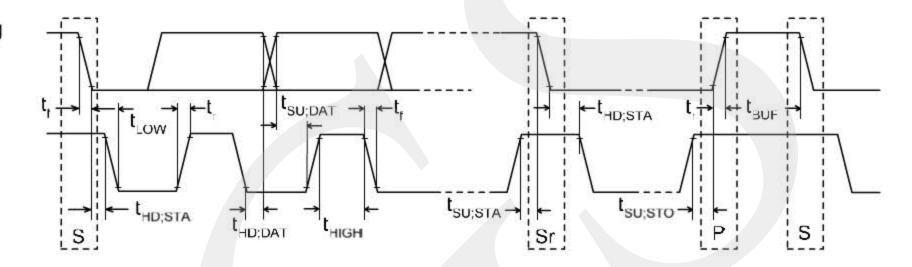


Timing Relationship (Using I²S format as an example)



Symbol	Parameter	Min	Тур	Max	Units
t _{LR}	LRCIN Period (1/F _S)	10.41	<u>82—8</u> 1	31.25	μs
t _{BL}	BCLK Rising Edge to LRCIN Edge	50	<u>19</u>	2 <u></u> 21	ns
t _{LB}	LRCIN Edge to BCLK Rising Edge	50	823	(/ ;	ns
t _{BCC}	BCLK Period (1/64F _S)	162.76		488.3	ns
t _{BCH}	BCLK Pulse Width High	81.38	8-8	244	ns
t _{BCL}	BCLK Pulse Width Low	81.38	1 1 - 1 2	244	ns
t _{DS}	SDATA Set-Up Time	50	<u> </u>	2	ns
ton	SDATA Hold Time	50		<u>-</u>	ns

• I²C Timing



Doromotor	Symbol	Standard	Mode	Mode Fast Mode		Linit
Parameter	Symbol	MIN.	MAX.	MIN.	MAX.	Unit
SCL clock frequency	f _{SCL}	0	100	0	400	kHz
Hold time (repeated) START condition	t _{HD,STA}	4.0	(200-30)	0.6	==	μs
LOW period of the SCL clock	t _{LOW}	4.7	(<u>1</u> 2)	1.3	<u>8_8</u>	μs
HIGH period of the SCL clock	t _{HIGH}	4.0		0.6		μs
Setup time for a repeated START condition	t _{SU;STA}	4.7	-	0.6	_	μs
Data hold time for I ² C bus devices	t _{HD;DAT}	0	3.45	0	0.9	μs
Data setup time	t _{SU;DAT}	250	=	100	-	ns
Rise time of both SDA and SDL signals	t _r	\$ 7.5	1000	20+0.1Cb	300	ns
Fall time of both SDA and SDL signals	t _f	@ <u></u>	300	20+0.1Cb	300	ns
Setup time for STOP condition	t _{SU;STO}	4.0		0.6		μs
Bus free time between a STOP and START condition	t _{BUF}	4.7	===	1.3	_	μs
Capacitive load for each bus line	C _b	# <u></u>	400	<u>12—</u> 21	400	pF
Noise margin at the LOW level for each connected device (including hysteresis)	V _{nL}	0.1V _{DD}	-	0.1V _{DD}	_	V
Noise margin at the HIGH level for each connected device (including hysteresis)	V _{nH}	0.2V _{DD}	-	0.2V _{DD}	<u>*-</u> 9	V

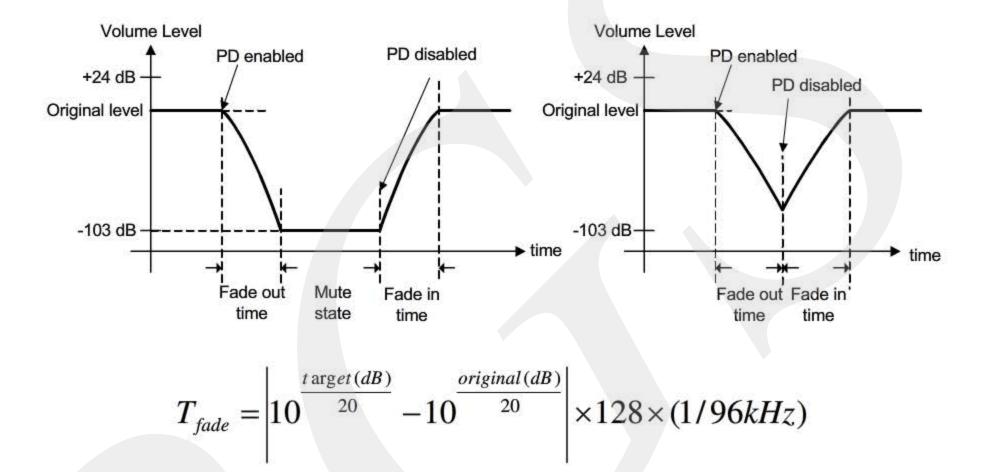
12. Operation Description

Reset

When the RESET pin is lowered, YDA179 will clear the stored data and reset the register table to default values. YDA179 will exit reset state at the 256th MCLK cycle after the RESET pin is raised to high.

Power down control

YDA179 has built-in volume fade-in/fade-out design for PD/Mute function. The relative PD timing diagrams for loudspeakers are shown below.



The volume level will be decreased to -∞dB over several LRCIN cycles. Once the fade-out procedure is finished, YDA179 will turn off the power stages, clock signals (for digital circuits) and current (for analog circuits). After PD pin is pulled low, YDA179 requires T_{fade} time to finish the forementioned work before entering power down state. Users can not program YDA179 during power down state. Also, all settings in the registers will remain intact unless DVDD is removed.

If the PD signal goes back to high in the middle of the fade-out procedure (above, right figure), YDA179 will execute the fade-in procedure. In addition, YDA179 will establish the analog circuits' bias current and send the clock signals to digital circuits. Afterwards, YDA179 resumes normal operation.

Internal PLL (PLL)

YDA179 has a built-in PLL with multiple MCLK/FS ratio, which is selected by I²C control interface. If PLL pin is pulled low, the built-in PLL is enabled; when PLL pin is pulled high, an external clock source for MCLK less than 50MHz must be provided. The MCLK/FS ratio will be fixed at 1024x, 512x, or 256x with a sample frequency of 48kHz, 96kHz, or 192kHz respectively.

When using YDA179 without I2C control interface, the operation is as follows.

PLL pin is set to high:

Internal PLL is bypassed(Disable). The following master clock frequency can be inputted into a MCK pin. A carrer clock frequency is the frequency divided by 128 of the following each inputted master clock.

*When the following master clock frequency cannot be inputted,/PLL is set low suggested.

Fs	MCLK frequency
48kHz	49.152MHz
44.1kHz	45.158MHz
32kHz	32.768MHz

PLL pin is set to low:

Internal PLL is enabled. The master clock inputted into the MCK pin becomes the frequency of quad edge evaluation. A carrier clock frequency is the frequency divided by 128 of the frequency of quad edge evaluation. (Divided by 32 of the frequency of master clock inputted into the MCK.)

Anti-pop design

YDA179 will generate appropriate control signals to suppress pop sounds during initial power on/off, power down/up, mute, and volume level changes.

Default volume (DEF)

The volume of YDA179 is +1.625dB when DEF pin is high, and the volume is muted when DEF pin low. When using YDA179 without I²C control interface, user should set the pin high. The user can change the values of the register table setting for volume control. For detailed information, refer to the register table section.

Self-protection circuits

YDA179 has built-in protection circuits including thermal, short-circuit and under-voltage detection circuits.

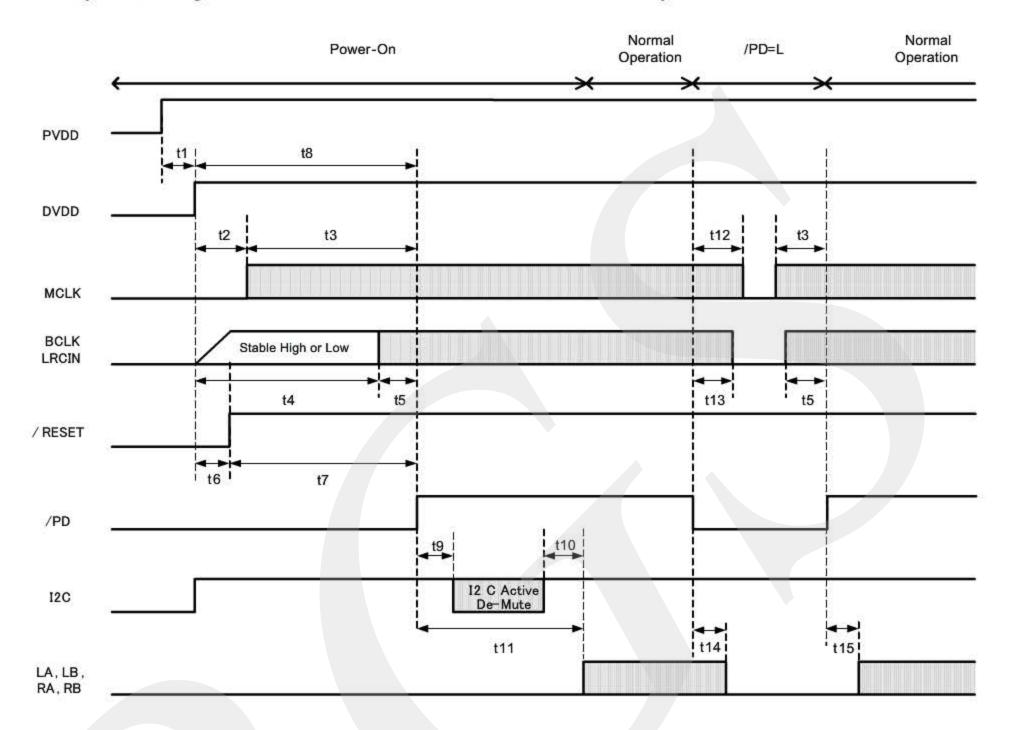
- (i) When the internal junction temperature is higher than 160 °C, power stages will be turned off and YDA179 will return to normal operation once the temperature drops to 125 °C. The temperature values may vary around 10%.
- (ii) The short-circuit protection circuit protects the output stage when the wires connected to loudspeakers are shorted to each other or GND/VDD. For normal 22V operations, the current flowing through the power stage will be less than 5A for stereo configuration. Otherwise, the short-circuit detectors may pull the ERROR pin to DGND, disabling the output stages. When the over-temperature or short-circuit condition occurs, the open-drain ERROR pin will be pulled low and latched into ERROR state. Once the over-temperature or short-circuit condition is removed, YDA179 will exit ERROR state when one of the following conditions is met: (1)RESET pin is pulled low, (2)PD pin is pulled low, (3) Master mute is enabled through the I²C interface.
- (iii) Once the DVDD voltage is lower than 2.7V, YDA179 will turn off its loudspeaker power stages and cease the operation of digital processing circuits. When DVDD becomes larger than 2.8V, YDA179 will return to normal operation.
- (iv) If the master clock inputted into MCLK pin stops during the period for 500 ns or more, YDA179 detect the stop of MCK. In this state, amplifier outputs are forced to Weak Low. If master clock is inputted normally again, ERROR pin is set to low. YDA179 won't leave ERROR state until one of the following conditions: (1) RESET pin is pulled low, (2) PD pin is pulled low, (3) Programming master mute via I²C interface.

PD pin is set to low, when stop the clock inputted into MCLK, BCLK, and LRCIN during operation.

(v) If it will be in the state where PVDD power supply is OFF and DVDD power supply is ON, ERROR pin is set to Low.

Power on sequence

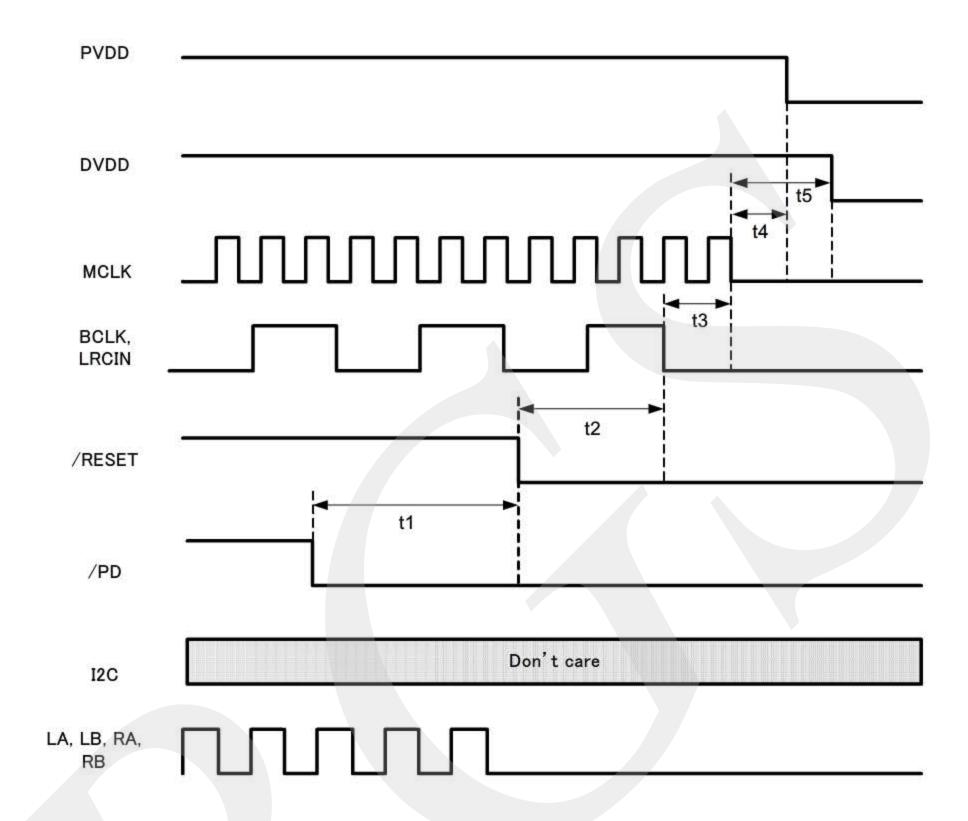
YDA179's power on sequence is shown below. Please note that we suggest users set DEF pin at low state initially, and then give a de-mute command via I²C when the whole system is stable.



Symbol	Condition	Min	Max	Units
t1		0	74.	msec
t2		0	7-1	msec
t3		10	0=0	msec
t4		0	-	msec
t5		10	74:	msec
t6		3	8 = 3	msec
t7		0	7 <u>=</u> 3	msec
t8		200	0 <u>=</u> 0	msec
t9		20	6 <u>2</u> 0	msec
t10	DEF=L	2	0.1	msec
t11	DEF=H	<u>=</u>	0.1	msec
t12		25	22	msec
t13		25		msec
t14		3	22	msec
t15	DEF= L or H	=	0.1	msec

Power off sequence

YDA179's power off sequence is shown below.



Symbol	Condition	Min	Max	Units
	With I ² C Control	35	-	maaa
t1	Without I ² C Control	5	S#8	msec
t2		0 (*1)	-	msec
t3		0	-	msec
t4		1	-	msec
t5		1		msec

Note *1: When t2 is less than 0.1 msec, pop noise may occur.

13. I2C-Bus Transfer Protocol

Introduction

YDA179 employs I²C-bus transfer protocol. Two wires, serial data and serial clock carry information between the devices connected to the bus. Each device is recognized by a unique 7-bit address and can operate as either a transmitter or a receiver. The master device initiates a data transfer and provides the serial clock on the bus. YDA179 is always an I²C slave device.

Protocol

START and STOP condition

START is indicated by a high to low transition of the SDA signal. A START condition must precede any command for data transfer. A STOP is indicated by a low to high transition of the SDA signal. A STOP condition terminates communication between YDA179 and the master device on the bus. In both START and STOP, the SCL is stable in the high state.

Data validity

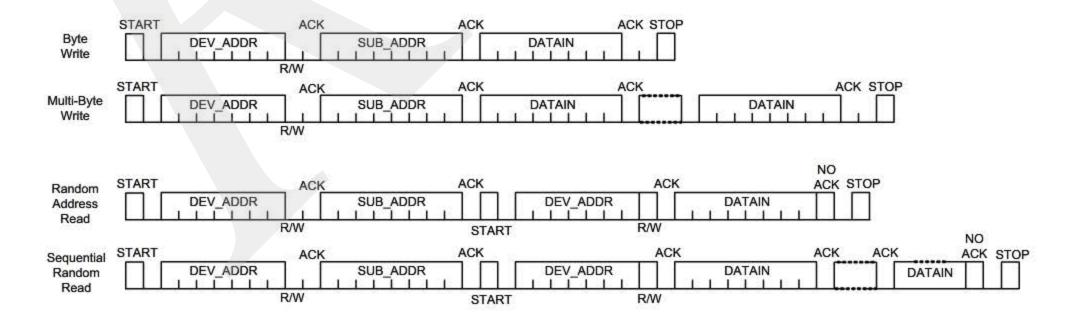
The SDA signal must be stable during the high period of the clock. The high or low change of SDA only occurs when SCL signal is low. YDA179 samples the SDA signal at the rising edge of SCL signal.

Device addressing

The master generates 7-bit address to recognize slave devices. When YDA179 receives 7-bit address matched with 0110x0y (where x and y can be selected by external SA0 and SA1 pins, respectively), YDA179 will acknowledge at the 9th bit (the 8th bit is for R/W bit). The bytes following the device identification address are for YDA179 internal sub-addresses.

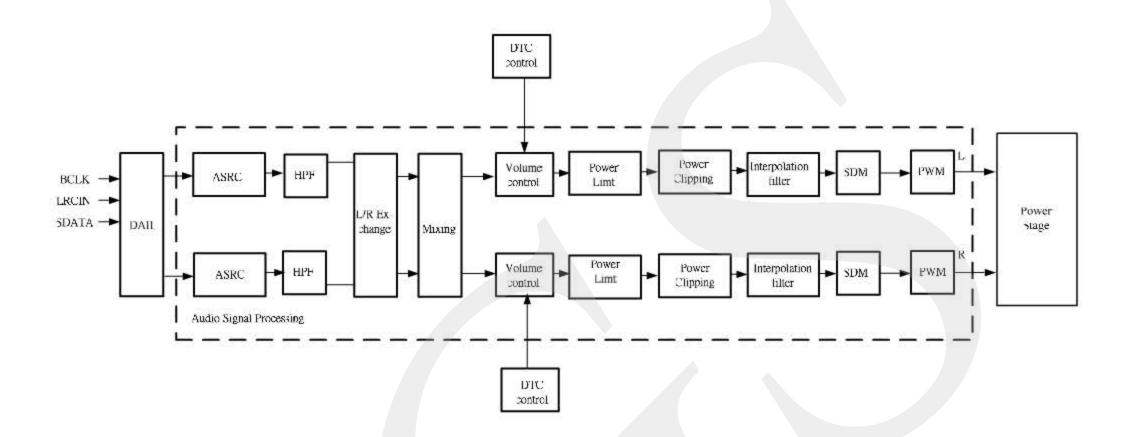
Data transferring

Each byte of SDA signaling must consist of 8 consecutive bits, and the byte is followed by an acknowledge bit. Data is transferred with MSB first, as shown in the figure below. In both write and read operations, YDA179 supports both single-byte and multi-byte transfers. Refer to the figure below for detailed data-transferring protocol.



14. Register Table

The audio signal processing data flow is shown in figure below. Users can control these function by programming appropriate setting to register table. In this section, the register table is summarized first. The definition of each register follows in the next section.



Address	Register	B[7]	B[6]	B[5]	B[4]	B[3]	B[2]	B[1]	B[0]
0X00	SCTL1	IF[2]	IF[1]	IF[0]	LREXC	PWML_X	PWMRX	Reserved	NGE
0X01	SCTL 2	Rese	rved	FS[1]	FS[0]	PMF[3]	PMF[2]	PMF[1]	PMF[0]
0X02	SCTL 3	EN_CLKO	НРВ	LV_UVSEL	SW_RSTB	MUTE	CM1	CM2	CompSDMEn
0X03	MVOL	MV[7]	MV[6]	MV[5]	M∨[4]	MV[3]	MV[2]	M∨[1]	MV[0]
0X04	C1VOL	C1V[7]	C1V[6]	C1V[5]	C1V[4]	C1V[3]	C1V[2]	C1V[1]	C1V[0]
0X05	C2VOL	C2V[7]	C2V[6]	C2V[5]	C2V[4]	C2V[3]	C2V[2]	C2V[1]	C2V[0]
0X06	HVUV	DIS_HVUV		Reserved		HVUVSEL[3]	HVUVSEL[2]	HVUVSEL[1]	HVUVSEL[0]
0X07	SCTL 4	Rese	rved	PC_EN	DRC_EN		Res	erved	Ye
0X08	LAR	LA[3]	LA[2]	LA[1]	LA[0]	LR[3]	LR[2]	LR[1]	LR[0]
0X09	Х				R	eserved			
0X0A	Х				R	eserved			
0X0B	OC SET				R	eserved			
0X0C	STATUS				R	eserved			
0X0D	ACFG				R	eserved			
0X0E	TM_CTRL				R	eserved			
0X0F	PWM_CTRL	Reserved							
0X10	ATT	3	Reserved ATT[4]			ATT[3]	ATT[2]	ATT[1]	ATT[0]
0X11	ATM	ATM[7]	ATM[6]	ATM[5]	ATM[4]	ATM[3]	ATM[2]	ATM[1]	ATM[0]
0X12	ATB	ATB[7]	ATB[6]	ATB[5]	ATB [4]	ATB [3]	ATB [2]	ATB [1]	ATB [0]

PRELIMINARY YDA179

)	(DA179
0X13	PCT	2	Reserved		PCT[4]	PCT[3]	PCT[2]	PCT[1]	PCT[0]
0X14	PCM	PCM[7]	PCM[6]	PCM[5]	PCM[4]	PCM[3]	PCM[2]	PCM[1]	PCM[0]
0X15	PCB	PCB[7]	PCB[6]	PCB[5]	PCB [4]	PCB [3]	PCB [2]	PCB [1]	PCB [0]
0X16	NGG		Reserved		DIS_ZD _FADE	Rese	erved	NG_GAIN[1]	NG_GAIN[0]
0X17	VFT	MV_FT[1]	MV_FT[0]	C1V_FT[1]	C1V_FT[0]	C2V_FT[1]	C2V_FT[0]	Res	erved
0X18	DTC	DTC_EN	DTC_TH[1]	DTC_TH[0]	DTC_RATE[1]	DTC_RATE[0]		Reserved	
0X19) .		Re	eserved			
0X1A	NGALT	NGALT[7]	NGALT[6]	NGALT[5]	NGALT[4]	NGALT[3]	NGALT[2]	NGALT[1]	NGALT[0]
0X1B	NGALM	NGALM[7]	NGALM[6]	NGALM[5]	NGALM[4]	NGALM[3]	NGALM[2]	NGALM[1]	NGALM[0]
0X1C	NGALB	NGALB[7]	NGALB [6]	NGALB [5]	NGALB [4]	NGALB [3]	NGALB [2]	NGALB [1]	NGALB [0]
0X1D	NGRLT	NGRLT[7]	NGRLT[6]	NGRLT[5]	NGRLT[4]	NGRLT[3]	NGRLT[2]	NGRLT[1]	NGRLT[0]
0X1E	NGRLM	NGRLM[7]	NGRLM[6]	NGRLM[5]	NGRLM[4]	NGRLM[3]	NGRLM[2]	NGRLM[1]	NGRLM[0]
0X1F	NGRLB	NGRLB[7]	NGRLB [6]	NGRLB[5]	NGRLB[4]	NGRLB [3]	NGRLB [2]	NGRLB [1]	NGRLB [0]
0X20	DRC_ECT	DRC_ECT[7]	DRC_ECT[6]	DRC_ECT[5]	DRC_ECT[4]	DRC_ECT[3]	DRC_ECT[2]	DRC_ECT[1]	DRC_ECT[0]
0X21	DRC_ECB	DRC_ECB[7]	DRC_ECB[6]	DRC_ECB[5]	DRC_ECB[4]	DRC_ECB[3]	DRC_ECB[2]	DRC_ECB[1]	DRC_ECB[0]
0X22	RTT	0	Reserved		RTT[4]	RTT[3]	RTT[2]	RTT[1]	RTT[0]
0X23	RTM	RTM[7]	RTM[6]	RTM[5]	RTM[4]	RTM[3]	RTM[2]	RTM[1]	RTM[0]
0X24	RTB	RTB[7]	RTB[6]	RTB[5]	RTB [4]	RTB [3]	RTB [2]	RTB [1]	RTB [0]

15. Detail Description for Registers

In this section, please note that the value in the highlighted columns shows the default value for those registers. If no highlighted, it is because the default setting of this bit is determined with external pin strapping.

Address 0X00 : State control 1
 YDA179 support multiple serial data input formats including I²S, Left-alignment and Right-alignment.
 These formats is chosen by user via bit7~bit5 of address 0.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
			000	I ² S 16-24 bits
			001	Left-alignment 16-24 bits
			010	Right-alignment 16 bits
B[7:5]	IF[2:0]	Input Format	011	Right-alignment 18 bits
			100	Right-alignment 20 bits
			101	Right-alignment 24 bits
			other	Reversed
DIAI	LREXC	Left/Right (L/R)	0	No exchanged
B[4]	LKEAC	Channel exchanged	1	L/R exchanged
וניום	D/A/A/I V	LA/LB evelopes	0	No exchange
B[3]	PWML_X	LA/LB exchange	1	Exchange
Dioi	DWAD V	DA/DD	0	No exchange
B[2]	PWMR_X	RA/RB exchange	1	Exchange
B[1]	×	Reserved		
DIOI	NGE	Noise gate enable	0	Disable
B[0]	NGE	Noise gate enable	1	Enable

Address 0X01 : State control 2

YDA179 has built-in PLL which can be bypassed by pulling PLL line high. When PLL is enabled, multiple MCLK/FS ratio is supported. Table below details the setting.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
B[7:6]	Х	Reserved		
	2		00	32/44.1/48kHz
DIE:41	F0	Complian Francisco	01	32/44.1/48kHz
B[5:4]	FS	FS Sampling Frequency	10	64/88.2/96kHz
			11	128/176.4/192kHz

Multiple MCLK/FS ratio setting table

BIT	NAME	DESCRIPTION	VALUE	B[5:4]=00/01	B[5:4]=10	B[5:4]=11
				Reset	Reset	Reset
		Multiple	0001	Default	Default	Default
D[0.0]	DME(2.01	Multiple F[3:0] MCLK/FS ratio		(256x)	(128x)	(64x)
B[3:0]	PMF[3:0]		0010	512x	256x	128x
			0011	768x	384x	192x
			0100	1024x	512x	256x

Address 0X02 : State control 3

To prevent the DC current from damaging the speaker, a high pass filter (3dB frequency = 5Hz) is built into the YDA179. It can be enabled or disabled by bit 6 at address 2.

YDA179 has master mute as well as individual channel mute. When the master mute is enabled, both left and right processing channels are muted. Individual channels can be muted by using the channel mute. When the mute function is enabled or disabled, the fade-out or fade-in process will be initiated.

The default settings of B[3:1] are determined by DEF pin. When DEF pin is pulled low or high, the default setting is muted or unmated.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
D[7]	EN_CLK_	PLL Clock Output	0	Disabled
B[7]	OUT	FLL Clock Output	1	Enabled
DIGI	НРВ	DC blocking HPF	0	Enable
B[6]	ПГБ	bypass	1	Disabled
DIEI	11/ 11/651	LV under voltage	0	2.7V
D[O]	B[5] LV_UVSEL	selection	1	3.0V
DIAI	CW DOTD	SW_RSTB Software reset	0	Reset
B[4]	SW_RSIB		1	Normal operating
Droi	MUTE	Montor Muto	0	Un-Mute (DEF=1)
B[3]	MUTE	Master Mute	1	Mute (DEF=0)
Droi	0144	Charact 4 Marta	0	Un-Mute (DEF=1)
B[2]	CM1	Channel 1 Mute	1	Mute (DEF=0)
DIAI	CMO	Observal O Moto	0	Un-Mute (DEF=1)
B[1]	CM2	Channel 2 Mute	1	Mute (DEF=0)
DIO1	CompCDME	Compensate SDM	0	Disable
B[0]	CompSDMEn	frequency response	1	Enable

Address 0X03 : Master volume

YDA179 supports both master-volume and channel-volume control for the stereo processing channels. Both master volume control (Address 0X03) and channel volume (Address 0X04 and 0X05) settings range from +12dB \sim -102dB. Given master volume level, say, Level A (in dB unit) and channel volume level, say Level B (in dB unit), the total volume equals to Level A plus with Level B and its range is from +24dB \sim -102dB, i.e., -103dB \leq Total Volume (Level A + Level B) \leq +24dB.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
			00000000	+12dB
			0000001	+11.5dB
			00000010	+11dB
			:	:
		Master Volume	00010111	0.5dB
D[7.0]	MV/17.01		00011000	0dB
B[7:0]	MV[7:0]		00011001	-0.5dB
			:	i :
			11100110	-103dB
			11100101	-∞dB
			1	
			1111111	-∞dB

Address 0X04 : Channel1 volume

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
			00000000	+12dB
			00000001	+11.5dB
			:	ä
			00010100	2dB
			:	:
D[7:0]	C41/[7:0]	Channel 1 Volume	00011000	0dB
B[7:0]	C1V[7:0]		00011001	-0.5dB
			:	:
			11100110	-103dB
			11100101	-∞dB
			:	1
			1111111	-∞dB

Address 0X05 : Channel2 volume

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
			00000000	+12dB
			0000001	+11.5dB
				1
			00010100	2dB
		Channel 2 Volume	1	1
D[7.0]	C0\([7.0]		00011000	0dB
B[7:0]	C2V[7:0]		00011001	-0.5dB
			;	i
			11100110	-103dB
			11100101	-∞dB
			;	:
			1111111	-∞dB

Address 0X06: Under voltage threshold for high voltage supply
 YDA179 provides HV under voltage detection which can be enable or disable via bit 7. The under-voltage detection level is programmable via bit3~ bit0. Once the output stage voltage drops below the preset value (see table), YDA179 will fade out audio signals to turn off the speaker.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
D(71	Die HV/IIV	Disable HV under	0	Enable
B[7]	Dis_HVUV	voltage circuit	1	Disable
B[6:4]	X	Reserved		
			Other	9.7V
			1100	19.5V
D[2:0]	HVI VEEL 12:01	HV Under Voltage	0100	15.5V
B[3:0]	HVUVSEL[3:0]	selection (Active)	0011	13.2V
			0001	9.7V
			0000	8.2V

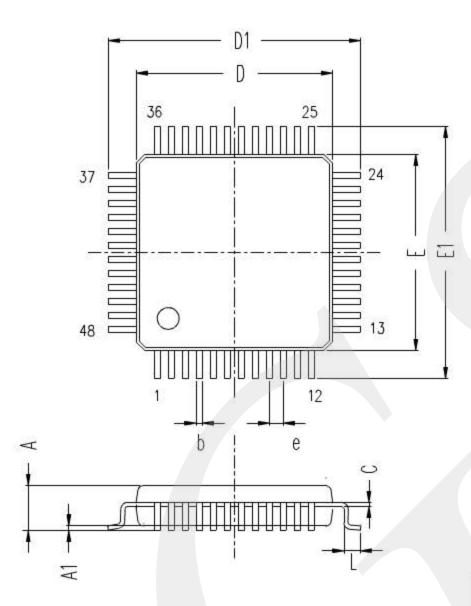
Address 0X07 : State control 4

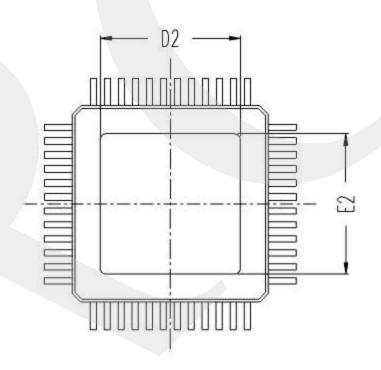
YDA179 provides channel mix, power clipping, and dynamic range control (DRC) function. These functions can be enable or not as the following table.

BIT	NAME	DESCRIPTION	VALUE	FUNCTION
B[7]	Х	Reserved		
B[6]	Х	Reserved		
B[5]	PC_EN	Power Clipping enable	0	Disable
			1	Enable
B[4]	DRC_EN	DRC enable	0	Disable
			1	Enable
B[3:0]	X	Reserved		

16. Package Dimensions

U-PK48SP2-S9-1





C L -1	Dimension in mm		
Symbol	Min	Max	
A	<u> </u>	1.60	
A1	0.05	0.15	
b	0.17	0.27	
С	0.09 6.90	0.20 7.10	
D			
D1	8.90	9.10	
E	6.90	7.10	
E1	8.90	9.10	
e	0.50BSC		
L.	0.45	0.75	

Exposed pad

	Dimension in mm		
	Min	Max	
D2	4.31	5.21	
E2	4.31	5.21	

- 注) 1. 表面実装LSIは、保管条件、および、半田付けについての特別な配慮が必要です。
 - 2. 組立工場により、寸法や形状などが異なる場合があります。 詳しくはヤマハ代理店までお問い合わせください。

Note: 1. Special attention needs to be paid to the storage conditions and soldering method of the surface mount IC.

2. Dimension, form, etc. may differ depending on assembly plants. For details, please contact your local Yamaha agent.



NOTICE The information provided is preliminary, and subject to change without notice. Please check for the latest information when using this product in your design.

AGENT _____

YAMAHA CORPORATION -

Address Inquiries to:

Semiconductor Sales & Marketing Department

■ Head Office 203, Matsunokijima, Iwata,

Shizuoka, 438-0192, Japan

Tel. +81-539-62-4918 Fax.+81-539-62-5054

■ Tokyo Office 2-17-11, Takanawa, Minato-ku,

Tokyo, 108-8586, Japan

Tel. +81-3-5488-5431 Fax.+81-3-5488-5088

■ Osaka Office Universal City Wako Bldg.

6-2-82, Shimaya, Konohana-ku, Osaka, 554-0024, Japan

Tel. +81-6-6465-0325 Fax.+81-6-6465-0391